

Increasing model-based decision strategies in humans



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Introduction

Humans are equipped with various strategies for solving problems. Two such strategies are **model-based** and **model-free** decision making [1].

Model-based strategies (*goal-directed* in psychology): Problem solvers employ an internal model, specifying which actions lead to which results in which states, to infer the sequence of actions that leads to the desired outcome.

Model-free strategies (*habitual* in psychology): Decisions are made by repeating action that previously led to reward. This leads to the formation of habits, stable stimulus-response associations.

Model-free strategies are fast and computationally cheap, but inflexible. Humans fall back to these strategies under stress [2]. **Model-based** strategies are flexible, but slow and demanding. They are better suited to attain long-term goals.

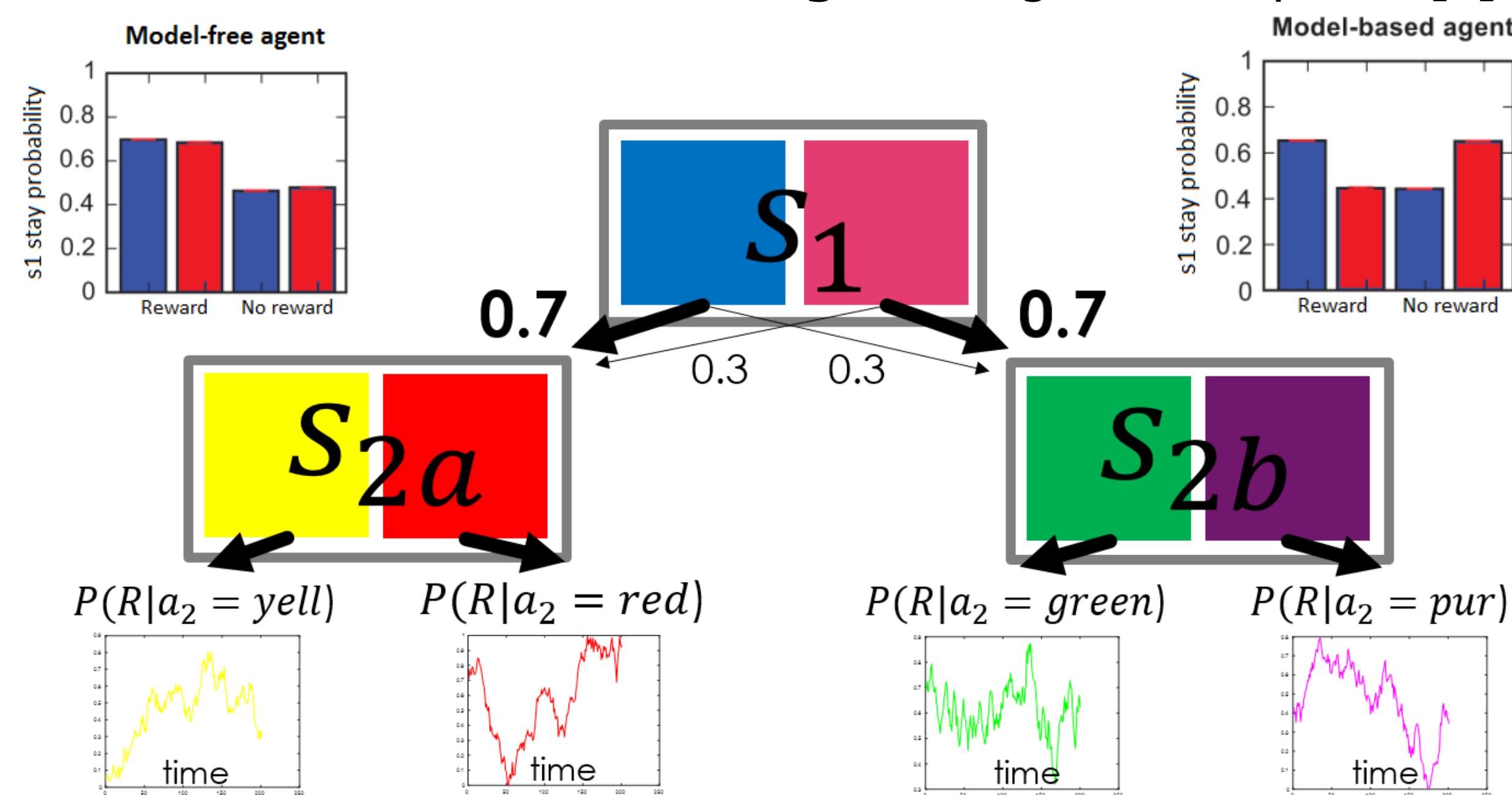
Research is lacking as to how model-based strategies can be improved.

Procedure

Overview.



Assessment of decision strategies using the 2-step task [3].



Model-based tasks, model-free tasks, or active control

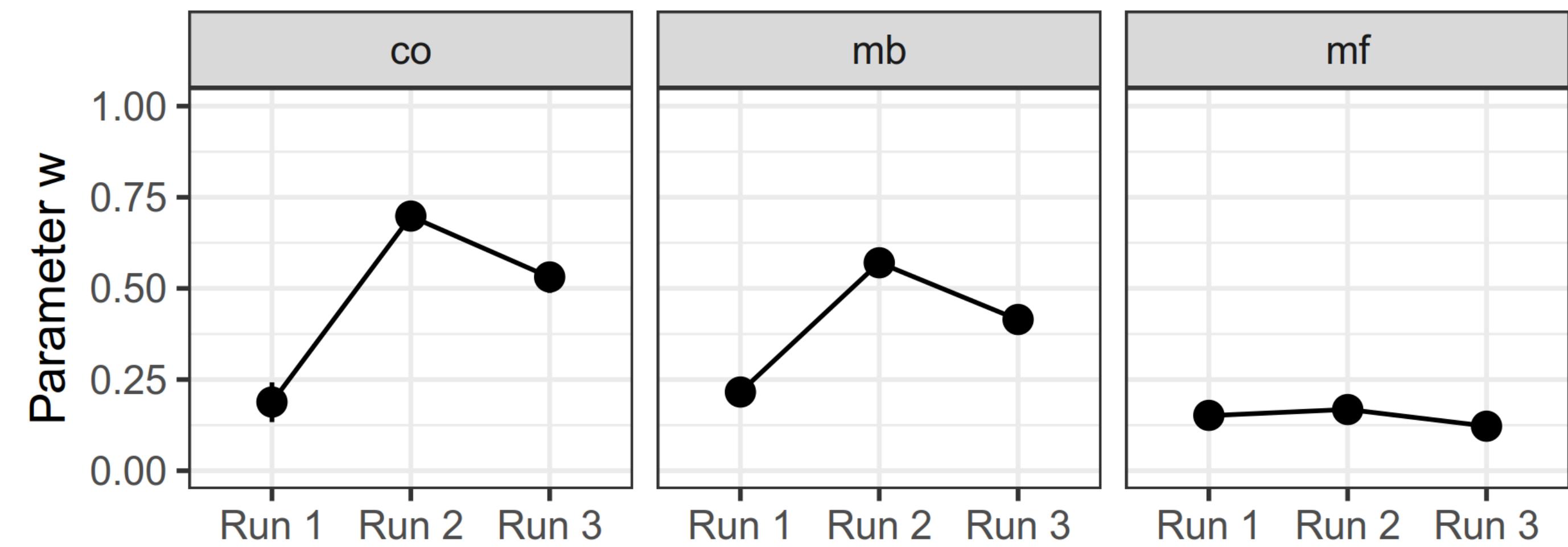
Model-based: Tower of London; rule-based category learning [4]

Model-free: Simple operant condition task [5]; information-integration category learning [4].

Control: Number comparison [6]; orientation discrimination [7].

Participants. 116 healthy young adults from UC Berkeley.

Training Effects: Computational Analysis



Parameter w increased in participants with model-based training (mb: $t(38)=8.7$, $p < 0.001$) and control (co: $t(18)=9.4$, $p < 0.001$), suggesting an **increase in model-based decision making**. Both run ($\chi^2(2)=170.6$, $p < 0.001$) and group ($\chi^2(2)=88.1$, $p < 0.001$) had significant effects on w . The interaction between run and group was also significant ($\chi^2(4)=94.8$, $p < 0.001$).

Computational Model

We used a reinforcement learning model reported previously [e.g., 8]. Agents select actions based on estimated values, using a softmax rule.

State-2 action values are updated using basic Rescorla-Wagner: $Q(s_2, a_2) = Q(s_2, a_2) + \alpha(r - Q(s_2, a_2))$

State-1 action values are updated in two ways, **model-based**: $Q_{mb}(s_1, a_1) = \sum_{s_2} p(s_2|s_1, a_1) \cdot \max(Q_{mb}(s_2, a_2))$

and **model-free**:

$Q_{mf}(s_1, a_1) = Q_{mf}(s_1, a_1) + \alpha(\lambda Q_{mf}(s_2, a_2) - Q_{mf}(s_1, a_1))$

Final state-1 action values are a combination of model-based and model-free values: $Q(s_1, a_1) = w \cdot Q_{mb}(s_1, a_1) + (1 - w) \cdot Q_{mf}(s_1, a_1)$

This model was fit to participants' behavior using maximum likelihood in a hierarchical model.

Conclusion

Model-based decision making was evident after all three trainings, and *increased* after model-based training and control.

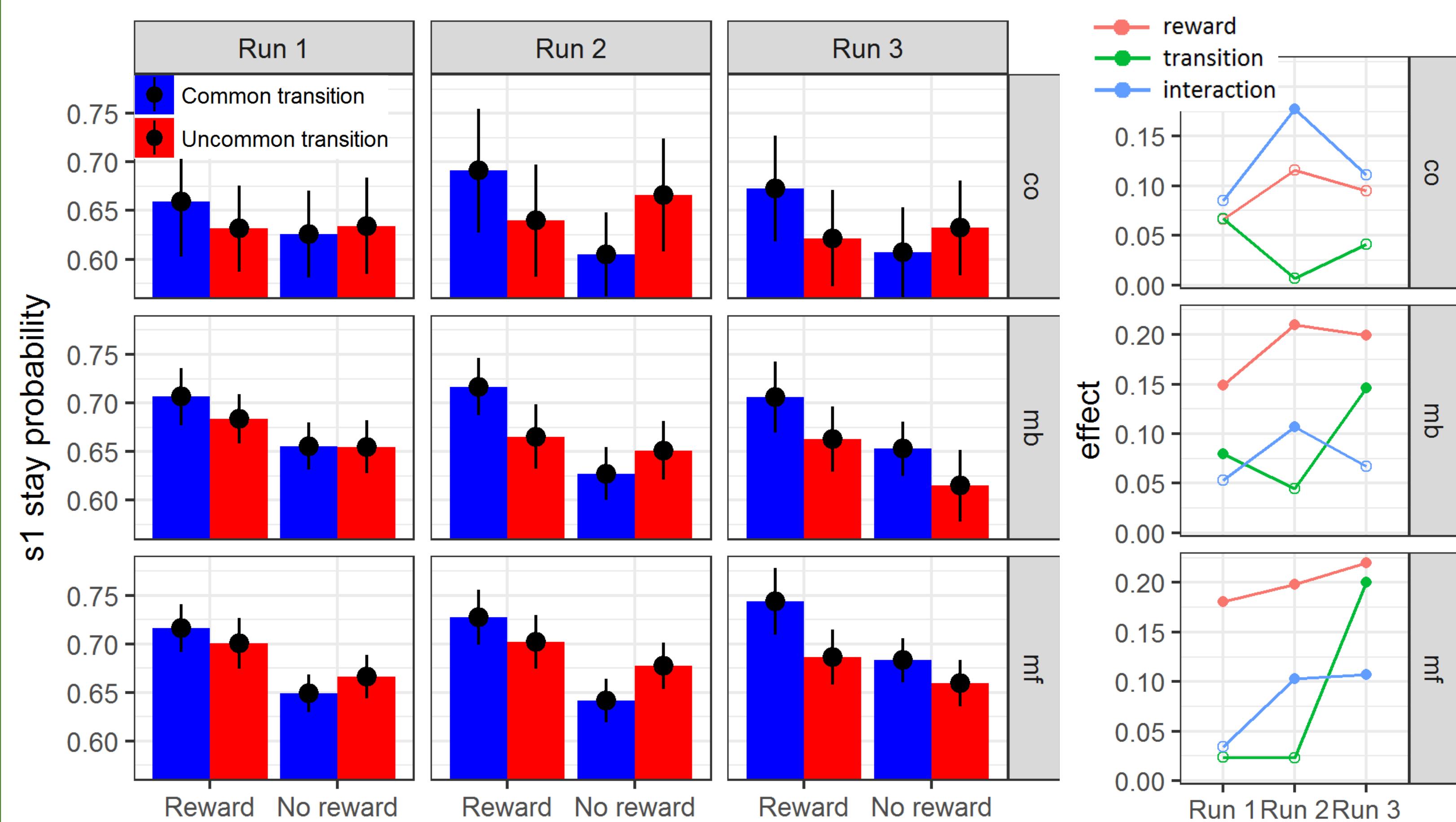
Behavioral analyses showed that participants took the model of the task into account after training, but not before (*model-based* component). Participants were sensitive to reward at all times (*model-free* component).

Computational modeling showed that *model-based decision making increased significantly* after training compared to before in the model-based and control groups.

- References.**
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Training Effects: Behavioral Analysis



Model-based patterns were evident after all trainings: Run 2, interaction between reward and transition in control group (co: $\beta=0.18$, $z=2.05$, $p=0.040$); after model-based training (mb: $\beta=0.11$, $z=2.54$, $p=0.011$); and after model-free training (mf: $\beta=0.10$; $z=2.92$, $p=0.004$).

Model-free patterns (main effect of reward) were evident in model-based (mb) and model-free (mf) training groups in all runs (all $\beta>0.15$, all $z>3.41$, all $p < 0.001$).