

# Increasing model-based decision strategies in humans

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## Introduction

Humans are equipped with various strategies for solving problems. Two such strategies are **model-based** and **model-free** decision making [1].

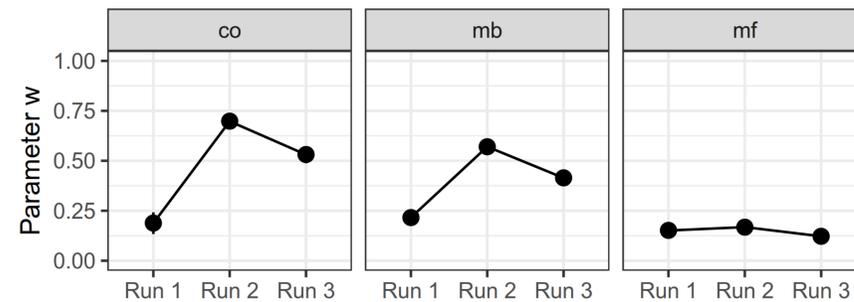
**Model-based strategies** (*goal-directed* in psychology): Problem solvers employ an internal model, specifying which actions lead to which results in which states, to infer the sequence of actions that leads to the desired outcome.

**Model-free strategies** (*habitual* in psychology): Decisions are made by repeating action that previously led to reward. This leads to the formation of habits, stable stimulus-response associations.

**Model-free** strategies are fast and computationally cheap, but inflexible. Humans fall back to these strategies under stress [2]. **Model-based** strategies are flexible, but slow and demanding. They are better suited to attain long-term goals.

*Research is lacking as to how model-based strategies can be improved.*

## Training Effects: Computational Analysis



Parameter  $w$  increased in participants with model-based training (mb:  $t(38)=8.7$ ,  $p < 0.001$ ) and control (co:  $t(18)=9.4$ ,  $p < 0.001$ ), suggesting an **increase in model-based decision making**. Both run ( $\chi^2(2)=170.6$ ,  $p < 0.001$ ) and group ( $\chi^2(2)=88.1$ ,  $p < 0.001$ ) had significant effects on  $w$ . The interaction between run and group was also significant ( $\chi^2(4)=94.8$ ,  $p < 0.001$ ).

## Computational Model

We used a reinforcement learning model reported previously [e.g., 8]. Agents select actions based on estimated values, using a softmax rule.

*State-2 action values* are updated using basic Rescorla-Wagner:  
 $Q(s_2, a_2) = Q(s_2, a_2) + \alpha(r - Q(s_2, a_2))$

*State-1 action values* are updated in two ways, **model-based**:  
 $Q_{mb}(s_1, a_1) = \sum_{s_2} p(s_2|s_1, a_1) \cdot \max(Q_{mb}(s_2, a_2))$

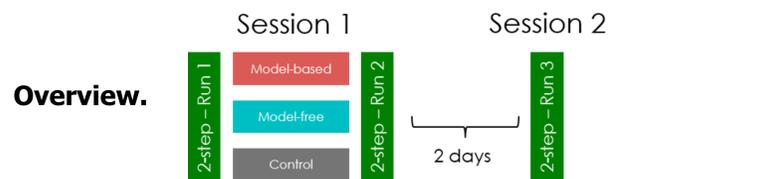
and **model-free**:

$Q_{mf}(s_1, a_1) = Q_{mf}(s_1, a_1) + \alpha(\lambda Q_{mf}(s_2, a_2) - Q_{mf}(s_1, a_1))$

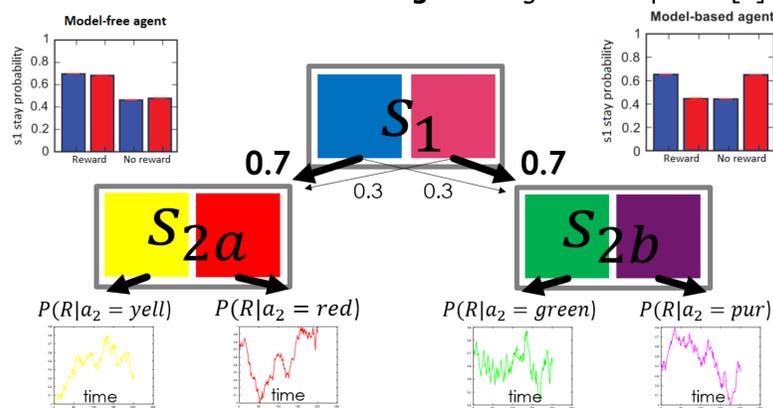
Final state-1 action values are a combination of model-based and model-free values:  $Q(s_1, a_1) = w \cdot Q_{mb}(s_1, a_1) + (1 - w) \cdot Q_{mf}(s_1, a_1)$

This model was fit to participants' behavior using maximum likelihood in a hierarchical model.

## Procedure



**Assessment of decision strategies** using the 2-step task [3].



**Model-based tasks, model-free tasks, or active control**

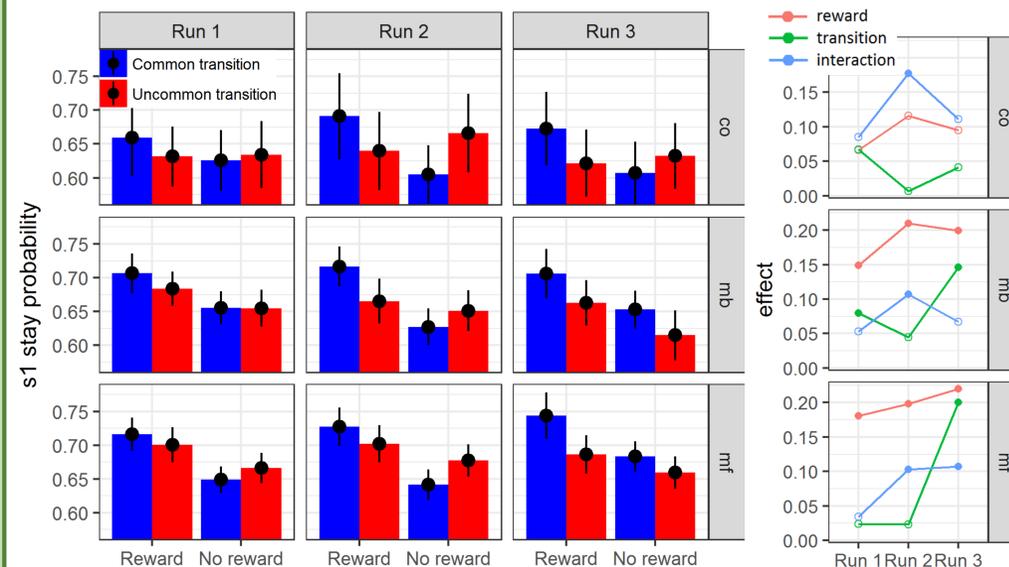
**Model-based:** Tower of London; rule-based category learning [4]

**Model-free:** Simple operant condition task [5]; information-integration category learning [4].

**Control:** Number comparison [6]; orientation discrimination [7].

**Participants.** 116 healthy young adults from UC Berkeley.

## Training Effects: Behavioral Analysis



**Model-based** patterns were evident after all trainings: Run 2, interaction between reward and transition in control group (co:  $\beta=0.18$ ,  $z=2.05$ ,  $p=0.040$ ); after model-based training (mb:  $\beta=0.11$ ,  $z=2.54$ ,  $p=0.011$ ); and after model-free training (mf:  $\beta=0.10$ ;  $z=2.92$ ,  $p=0.004$ ).

**Model-free** patterns (main effect of reward) were evident in model-based (mb) and model-free (mf) training groups in all runs (all  $\beta > 0.15$ , all  $z > 3.41$ , all  $p < 0.001$ ).

## Conclusion

*Model-based decision making* was evident after all three trainings, and *increased* after model-based training and control.

Behavioral analyses showed that participants took the model of the task into account after training, but not before (*model-based* component). Participants were sensitive to reward at all times (*model-free* component).

Computational modeling showed that *model-based decision making increased significantly* after training compared to before in the model-based and control groups.

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